# EMF – 18G Electric Field Probe USER MANUAL





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# **SAFETY INFORMATION**

Please read carefully the contents of this manual before using the product. In particular follow the safety recommendations, the instructions about operating procedures and handling of the product.



Do not install or substitute parts or perform unauthorized modifications to the instrument. Do not try to open or disassemble. Return the instrument to Microrad for maintenance and repair services.



This product is equipped whit a lithium ion rechargeable battery. Do not open or disassemble it, or use it in a humid or corrosive environment. Do not put, store or leave your product near sources of heat, in direct strong sunlight, in a high temperature place or in pressurized container. Use exclusively the provided battery charger.

#### INTRODUCTION

EMF-18G is an electric field isotropic sensor based on a new generation of diode dipoles.

Bandwidth, sensitivity and sampling speed specifications make this sensor unique in its kind.

EMF-18G has been designed keeping in mind the measure of the electric field inside TEM cells, GTEM cells, anechoic chambers; nevertheless it is very suitable for monitoring applications where electric field levels are critical or to preserve the human safety.

The sensor is self-powered by a professional lithium ion battery, that allows an autonomy up to 45 hours (depending on sampling speed setting). A complete battery charge takes about 2 hours and only 15 minutes of recharge are needed to make the sensor up to 3 hours operative. Furthermore this kind of battery does not suffer of memory effect and shows an excellent discharge curve.

The software application *EMCViewer* had been developed in order to interact with the EMF-18G sensor and to represent measured data coming from it. The communication link is based on a fiber optic cable and an Optical-USB adapter to avoid interference issues.

The number of EMF-18G sensors that can be simultaneously connected to the PC where the software application *EMCViewer* is running is virtually unlimited (at the moment it is possible to connect up to 8 sensors).

EMF-18G sensor offers flexibility of use, size, cost and safety features much better than laser powered systems.

# **EMF-18G SENSOR STRUCTURE AND ORIENTATION**

The wrapping of the EMF-18G sensor is made of thermoplastic resin characterized by low dielectric constant and low dissipation factor.

The dipoles are built using a thick film with distributed electric constants; they are mutually oriented at 54.7° in the space; on this way, the spatial distribution forms an equilateral triangle, with resistive paths from the dipoles to the amplifier input of the same size and orientation.

These specifications are the main elements underlying the extraordinary bandwidth of the EMF-18G sensor.

# **CONTROL PANEL**

The control panel is located at the bottom of the cylindrical stem of the sensor and it hosts the optical connector (*FIBER*), the battery recharging connector and charge in progress led (*CHARG*), the battery low led indicator (*B.LOW*) and the power switch (*PW*) that features an integrated blue led.



Fig. 1: Bottom view: EMF-18G control panel

# FIBER OPTICAL CABLE

A fiber optic link ensures noise and interference immunity during the measure operations. The supplied fiber optic cable has a length of 10 meters and is equipped on both side with identical male connectors; one side shall be inserted into the EMF-18G fiber connector, the other side into the Optical-USB adapter.

Optionally longer cables are available, in order to make connection links up to 40 meters.



Do not exceed a 10 cm bend radius when handling the fiber optic cable. Tight corners may affect the integrity of the cable and the resulting damage could be even irreversible. Take particular care when handling the fiber optic cable and absolutely avoid to disconnect the plug by pulling directly the fiber cable: the disconnection must be performed only by warily pulling on the knurled part of the connector, using the fingers.

# **OPTICAL-USB ADAPTER**

The Optical-USB adapter is the interface between the fiber optic cable and a standard USB cable that finally connects to the PC/Tablet. The adapter is USB powered.



It is recommended to always apply the provided silicone plugs to the fiber optic connectors of the EMF-18G sensor and of the Optical-USB adapter after use.

This ensures an effective protection from dust and other elements that may reduce or impair the efficiency of the optical link.

# **BATTERY RECHARGE**

The EMF-18G sensor alerts the user about a battery low condition: when the charge level drops below 5%, the red led *B.LOW* starts flashing. In this condition, it is preferable to stop the measure as soon as possible to avoid the sudden disruption of communication.

To resume the charge, it is sufficient to plug the provided battery charger to the *CHARG*. connector. The green led starts flashing until the charge reaches the 100%, then it goes off.

The total charging time, starting from a 10% residue, is about 2 hours; however it is possible to achieve a 10% level of charge increment in less than 20 minutes. When fully charged, the battery autonomy is about 45 hours, considering the EMF-18G sensor set to operate at 1 Hz sample rate.

Note: during the recharge time the EMF-18G sensor get a not operative state.

# MINIMUN SYSTEM REQUIREMENTS

The following minimum specifications are required for the PC/Tablet in order to proper work with the EMF 6E sensor and the *EMCViewer* software:

- Processor: 1GHz dual core 32 or 64 bit architecture.
- RAM: 2 GB.
- USB: availability of one free port for each sensor to interface.
- OS: Microsoft Windows XP, Vista, 7, 8; 32 or 64 bit.

# CONNECTION BETWEEN THE PC AND THE SENSORS

The sensor is connected to the PC through an interconnection kit that consists of:

- Fiber optic cable.
- Optic-USB adapter.
- USB cable.

When working with multiple EMF-18G sensors (up to 8 sensors) each one shall be connected to a different USB port of the PC, through its own cable kit.

Moreover each sensor shall be then turned on (*PW* button) so that it can be properly

detected by the software application *EMCViewer*.

Note: the power-on status of the sensor is indicated by the blinking blue led inside the power button.

#### **SOFTWARE INSTALLATION**

The installation file of the software application *EMCViewer* is usually supplied on a USB drive or is available on the Microrad internet site for download ( <u>www.microrad.it</u>); the filename of the installer file is <u>setup\_emcviewer\_X\_Y.exe</u> (where X and Y identify the major and minor number of the application release).

After launching the executable, a guided process of installation will configure the application on the PC in a few simple steps.

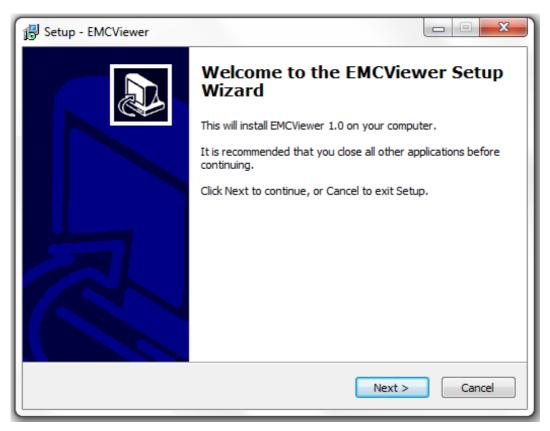


Fig. 2: Software application installation process

In addition, during the setup process, the drivers of the Optical-USB adapter are installed, allowing the automatic recognition whenever the adapter is connected to the PC.

At the end of the installation process a launch icon is created both on the desktop and the start menu of Windows.

Before starting the *EMCViewer* application ensure that the sensor (or, in the case of multiple connections, all the sensors you want to monitor) is connected and powered on.

The application software can be then started using the *EMCViewer* launch icon; a number of user interfaces that equals the number of sensors connected to the PC will appear on the screen.

# **SOFTWARE USER INTERFACE**

After the launch of the *EMCViewer* application, each user interface that is shown on the screen is associated with an EMF 6E sensor that is connected to the PC and powered on.

On the top bar of each user interface window is visible the name and version of the software application, followed by the Serial Number of the sensor associated with the interface.

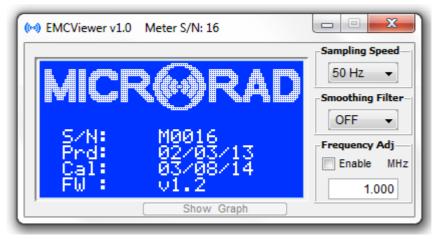


Fig. 3: User interface start-up phase

Furthermore during the start-up phase of each user interface, for few seconds, the following information about the connected sensor are shown:

- Serial Number (\$\mathbb{S}/\mathbb{N}).
- Date of production (**Prd**).
- Date of calibration (Cal).
- Firmware version (FW).

After that the interface enters the operating mode and the data presented on the screen are finally related to the measured value acquired by the sensor.

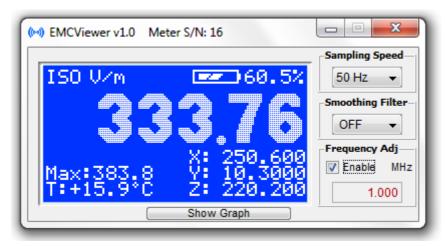


Fig. 4: Data display in operative mode

#### The available data are:

- Unit of measure of the electric field (V/m, A/m, W/m2 or mW/cm2, selectable in sequence by a left click of the mouse over the unit of measure text).
- · Battery level indicator, both graphical and as percentage value.
- Isometric value of measured field (the biggest font on the screen).
- Maximum value of the measured field (it is possible to clear this value by a left click of the mouse over it).
- Temperature (°C).
- · Measured field components on the single axes X, Y, Z.

# **SENSOR SETTINGS**

On the right side of the user interface there are 3 controls allowing to set the parameters that affect the acquisition behaviours of the EMF -18G sensor:

The Sampling Speed control sets the sampling rate of the acquisition; it is possible
to select one of the following values, reported in the same order of the combo box:

```
1 Hz, 2 Hz, 4 Hz, 8 Hz, 25 Hz, 50 Hz, 1/2 Hz, 1/4 Hz, 1/10 Hz, 1/20 Hz, 1/30 Hz
```

Increasing the sampling speed improves the time resolution, but raises the noise level affecting the measure. Running at 25 or 50 Hz, the noise level is greater, and in some conditions, dealing with low field levels (<5 V/m), the measure could be inaccurate; however such situation is highlighted by the *EMCViewer* user interface by changing the background from blue to red.

- The Smoothing Filter control allows to manage the behaviour of the smoothing filter; the purpose of this digital filter is the "flattening" of the fluctuations of the measured signal; it is possible to select the bandwidth of the filter among predefined values; the smaller the selected bandwidth, the greater the effect of the "softening". Depending on the selected sampling speed, the number of possible choices of the bandwidth is variable, with a maximum of four selectable bandwidths when 50 or 25 Hz sampling speed is selected. In case of sampling speed equal to or less than 1 Hz, the filter is forced into the OFF mode.
- The Frequency Adj control enables the correction of the measured values. As a matter of fact each EMF-18G sensor stores inside its non volatile memory a look up table needed for the correction of the measured value when the frequency of the signal under observation is known. The correction frequency range starts from a minimum of 0.01 MHz (10 KHz) up to 18,000 MHz (18 GHz), with steps of 0.001 MHz (1 KHz). If the check box is enabled, the fix for the selected frequency is applied, and the selected frequency value becomes red indicating that it is no more editable.

# **GRAPHICAL VISUALIZATION OF THE DATA**

The **Show/Hide Graph** button located at the bottom of the user interface opens/closes the window that shows the real-time plot of data coming from the sensor.

More specifically it is possible to view the time evolution of the isotropic values of measured field, its X, Y, Z components, and the temperature.

Electric field data are displayed according to the field unit (V/m, A/m, W/m2, mW/cm2) that was selected in the user interface, while temperature unit is °C.

The *Play / Stop* button performs the graphical data capture start and stop, manually; a blue vertical line inside the plot delimitates the various sessions of acquisition.

Altogether it is possible to keep in memory and to display up to 180,000 samples; for example it is possible to get 1 hour of data plot running at 50Hz sampling speed, 2 hours at 25 Hz, 50 hours at 1 Hz and so on.

After that, the older samples are discarded to host the newer ones according to a FIFO logic (First In First Out).

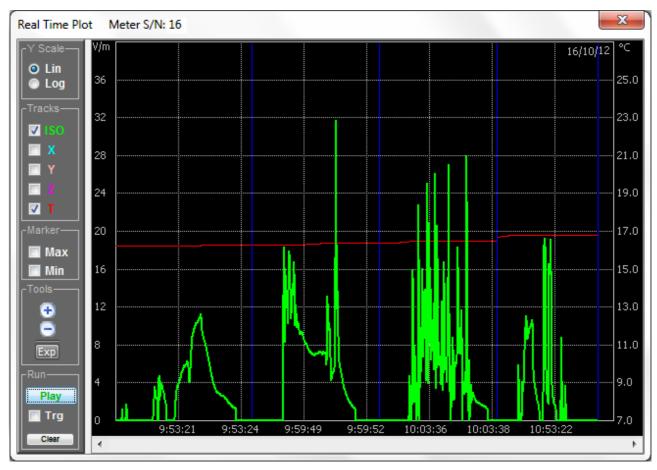


Fig. 5: Data graphical visualization

In addition the acquisition can be also controlled by a trigger logic; by activating the *Trg* checkbox, a dedicated panel asks to insert two thresholds: the first threshold is used to

automatically start the acquisition whenever the measured isotropic field exceeded it; the second one vice versa stops the acquisition each time the measured isotropic field falls below it. The unit of the thresholds are the same ones selected by the user interface for the electric field.



Fig. 6: Acquisition trigger settings

Finally, the *Clear* button deletes all data present in memory and clean up the plot.

By enabling the appropriate check-box in the *Tracks* control, it is possible to activate or deactivate the visualization of each individual track (ISO, X, Y, Z, T).

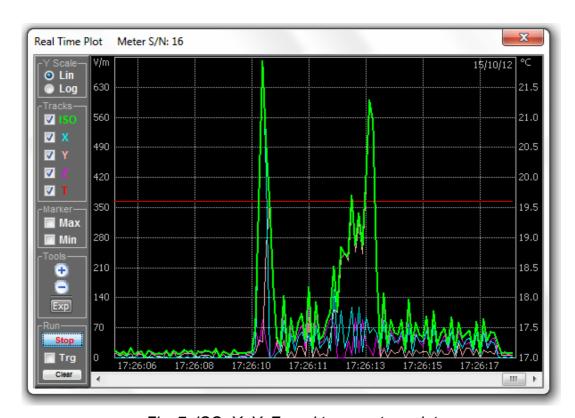


Fig. 7: ISO, X, Y, Z, and temperature plot

Under the horizontal axis, the time is reported using the *hours:minutes:seconds* format.

The date is shown in the upper right corner of the grid using the *day/month/year* format.

The + and - zoom buttons within the control **Tools** allow to expand or reduce the horizontal dimension of time displayed on the graph.

The **Y** Scale control toggles between linear and logarithmic scale for field values (while temperature is always displayed in linear scale); selecting the logarithmic scale, the 0 dB is dynamically assigned to the maximum isometric value E<sub>isomax</sub> (V/m) present in the plot; after that each point of value E (V/m) gets a corresponding value in decibels E (dB) according to the relation:

$$E (dB) = 20 Log_{10} \underline{E (V/m)}_{Lisomax (V/m)}$$

Thus all values shown, expressed in decibels units, are negative (<0dB); the lower values are clamped to -100 dB.

Note that in general, moving the mouse pointer over the chart, a *tooltip* appears showing the detailed field (or temperature) values relative to the point selected by the mouse pointer.

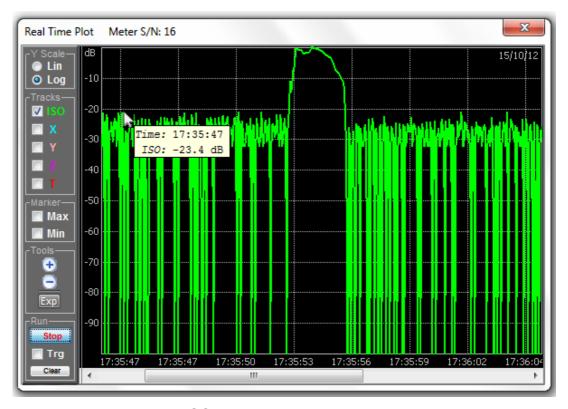


Fig. 8: ISO plot using the logarithmic scale

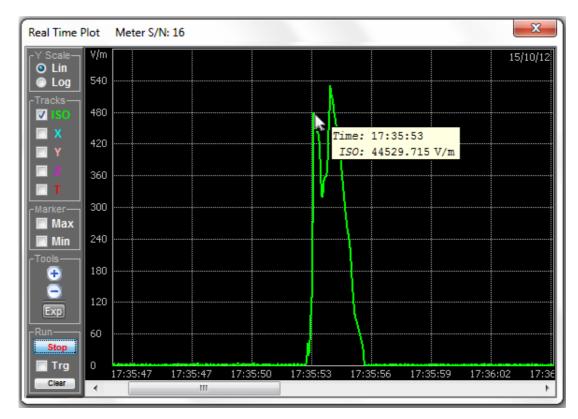


Fig. 9: Tooltip data on the mouse pointer

The *Marker* check boxes perform the highlight on the graph of the maximum and the minimum values for each enabled track.

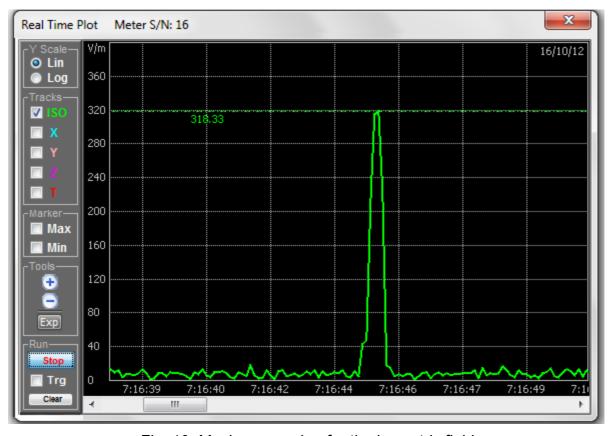


Fig. 10: Maximum marker for the isometric field

# **DATA AND IMAGE EXPORTATION**

The *Exp* button in the *Tools* control allows to export an image of the currently displayed plot, or to export row data.



Fig. 11: Exportation menu

Considering the image exportation, a dialog box lets to choose the format of the exported image, Bitmap (BMP) or JPEG (JPG); furthermore it is possible to select whether to export the plot using original colours (black background) or inverted colours (white background).

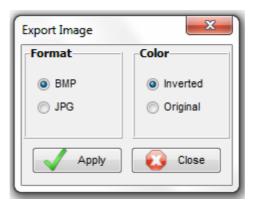


Fig. 12: Image export settings

Row data are exported using an Excel compatible format (.xls file).

Both for image or data exportation, the application asks the selection of the folder and the file name where exported data will be saved.

# **COMMUNICATION PROTOCOL**

Users can access EMF-18 data by means of custom software.

First is required to install on the PC the Virtual COM Port (VCP) driver from FTDIChip; this driver allows to access the USB port as a standard serial UART port.

Port settings must be: 8 bit data, no parity, 1 stop bit (8n1); speed 921600 bps.

Data are continuously sent from the EMF-18G according to the sampling settings (for instance if the sensor is set to work at 50Hz, EMF-18G sends 50 packets per second).

Each data packet is composed of 22 bytes and is organized according to the following format:

Byte	Valore
0	55h
1	99h
2	Ex 0
0 1 2 3 4 5 6 7	Ex 1
4	Ex 2
5	Ex 3
6	Ey 0
7	Ey 1
8	Ey 1 Ey 2
9	Ey 3 Ez 0
10	Ez 0
11	Ez 1
12	Ez 2
13	Ez 3
14	Temperature 0
15	Temperature 1
16	Temperature 2
17	Temperature 3
18	Battery Level
19	Reserved
20	CheckSum Low
21	CheckSum High

Tab. 1: Data packet format

Field and temperature data values are 32 bits (4 bytes indexed 0,1,2,3) single precision IEEE754 (IEC 60559). Byte with index 0 is the less significative.

The battery level is only one byte representing the charge percentage (0 to 100%).

The 16 bits checksum is the sum of all preceding packet bytes. (from byte 0 to 19).

Note that communication is mono-directional, from the EMF-18G sensor to the PC; for this reason the acquisition settings are only modifiable using the *EMCViewer* software. EMF-18G stores the settings on a non volatile memory and then keeps them also after power off.

#### FIRMWARE UPDATE

The following procedure details how to make a firmware update of the sensor:

- Connect the target sensor to the PC, without turning it on; note that for firmware update purposes, a multiple sensors connection is forbidden.
- Start the application *EMCViewer FwUpdate* from the Windows Start menu.
- Select and open the file containing the new firmware (.rom extension).
- A dialog box showing the text "Press OK to update" appears on the screen; do not press Ok for now.
- Turn on the sensor through the *PW* button and press the OK button within 4 seconds.

If the whole process was successful, the firmware of the sensor is updated in a few seconds and a message notifies about the end of the update and the reboot of the sensor; otherwise repeat from the first step.

# **PART LIST**

The sensor is supplied with the following parts:

- User manual in electronic format.
- Calibration certificate ISO 9001: 2008 IEEE std. 1309: 2005.
- 10 m fiber optic cable.
- USB-Optical adapter.
- USB cable.
- IP65 plastic case.

# **TECHNICAL SPECIFICATIONS**

Sensor Type	Isotropic Triaxial	
Measured Data	X,Y,Z and ISO	
Sensor Bandwidth	10 KHz ÷ 18 GHz	
Amplitude Response	100 KHz ÷ 1 GHz: +/- 1 dB	
	1÷ 18 GHz: +/- 3 dB	
Dynamic range	0,5 ÷ 500 V/m (60 dB)	
Linearity @ 100 MHz	2 ÷ 300 V/m 0,5 dB	
Isotropy @ 1,8 GHz	0,4 dB	
Temperature Stability	0,5 dB	
Maximum sampling rate	50 Hz (Tsample= 20 ms)	
Operating Temperature	+10 ÷ +40 °C	
Operating Humidity	5% ÷ 90% not condensated	
Weight	< 100g	
Size	Length: 135 mm,	
	Diameter: Max 60 mm Min 30 mm	

Tab. 2: Technical Specifications